Interactive Question Answering

Language learning using text-based games

Edan Toledo | Gregory Furman | Roy Cohen | Dr. Jan Buys | Dr. Jonathan Shock

Project Overview

We investigate three methods for training question-answering agents in text-based environments. Through interaction and observation, these agents were required to answer questions about objects located within dynamically created text games in an interactive questionanswering (IQA) setting.

A I MAS

Improve upon previous question-answering benchmarks.

Highlight the inferior sample efficiency of prior methods.

Environment

- Games are procedurally generated with each consisting of a number of rooms containing objects.
- Actions are natural language commands that consist of an action, modifier, and object i.e "eat red toast"

 Map types indicate the number of rooms in an environment. Fixed maps have 6 rooms. Random maps have between 2 and 12 rooms.

Jame	You find yourself in a backyard. You make out a patio table. You see a patio chair. It's stylish. In a corner you can see a BBQ. There's an open screen door leading south.
Juest	Where is the diced potato?
Igent	>Qapla'
Jame	That's not a verb I recognize.
Igent	>eat ghargh
Jame	You can't see any such thing.
Agent	>go south
1	You've just entered a kitchen. You can see an open fridge here. It is empty! You see a closed oven. Look over there,



it's a counter. On the counter you can see a diced potato, a red ghargh and a knife. There's an open door is leading north. Agent | >wait

Agent | >answer: kitchen

Game

Approaches

Sequence-Modelling

We investigated the effectiveness of a policybased reinforcement learning method along with a learned environment dynamics model to promote semantic encoding.

Policy-Based

The learned environment dynamics model aims to give the agent an understanding of the enviornment dynamics.



By framing IQA as an offline sequence modelling problem, we investigate the applicability of the novel Decision Transformer (DT) architecture. A sequence consists of states, actions, and rewards corresponding to each episodic timestep t.

A causally masked GPT-2 Transformer for action generation along with an answer prediction head for QA was used. Additionally, we trained a BERT model for question-answering to be used in tandem with the DT's command generation heads (DT-BERT).



Graph Attention Network

This method explores the use of Graph Attention Networks (GATs) in providing an RL agent with some contextual understanding of the environment with which it inhabits.

Context is provided by embedding specific details about an environment into a knowledge graph, which the GAT utilises to provide additional context to an agent.





